



Distributed and Collaborative Intelligent Systems and Technology (DCIST)

Collaborative Research Alliance (CRA)



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Distributed and Collaborative Intelligent Systems and Technology (DCIST)

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Vision:

Develop the underpinning science to extend the reach, situational awareness, and operational effectiveness of Intelligent System/Soldier teams against dynamic threats in complex and contested environments and provide technical and operational superiority through fast, intelligent, resilient, and collaborative behaviors.

Research Areas:

- Distributed Intelligence
- Heterogeneous Group Control
- Adaptive and Resilient Behaviors
- Cross Disciplinary Experimentation

Payoff:

- Speed of battle decision making, operation, and adaptation for highly distributed and collaborative heterogeneous teams of intelligent systems and Soldiers in complex and contested environments.
- Augmented capability of the collective team well beyond that of any one component.



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The Nation's Premier Laboratory for Land Forces

RA1 - Distributed Intelligence

- Hierarchical and composable models and abstractions
- Collaborative inference and decision making
- Distributed perception action communication loops

RA2 - Heterogeneous Group Control

- Contextual Abstractions for Heterogeneous Groups
- Synthesis of group behaviors and interactions
- Algorithms for Control of Heterogeneous Groups

RA3 - Adaptive and Resilient Behaviors

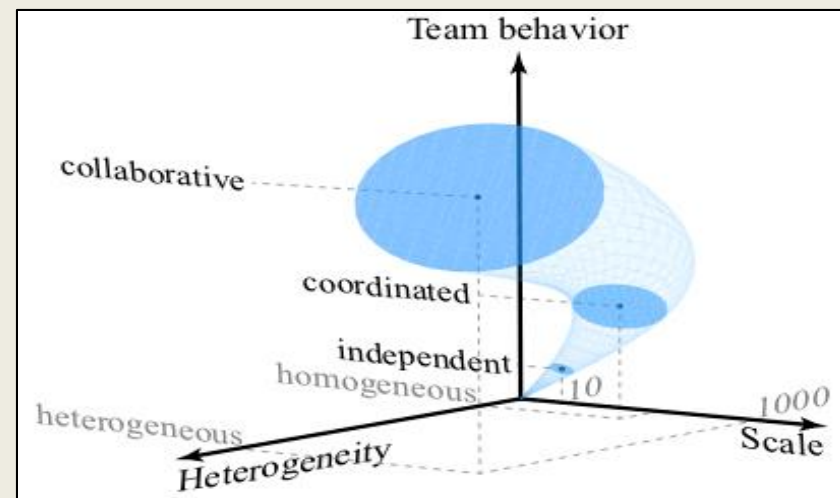
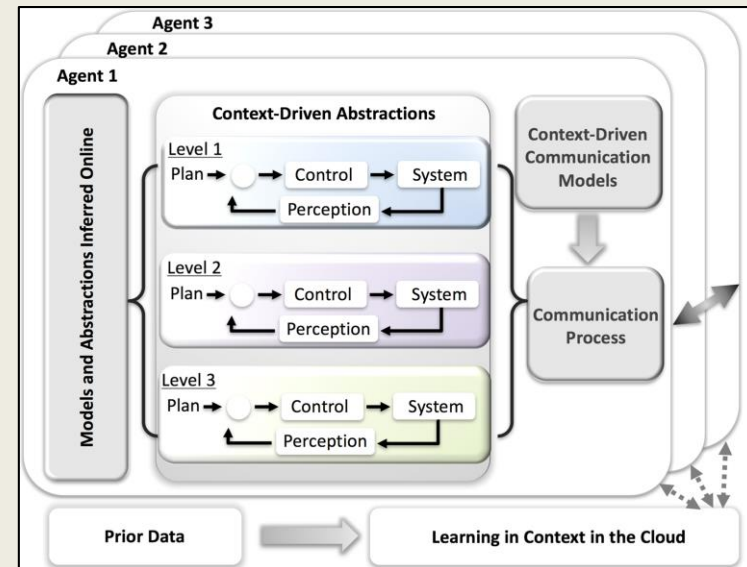
- Robust perception action and learning
- Information and adaptation for resilience
- Macro scale resiliency

CDE - Cross-Disciplinary Experimentation

- Open testbeds and common software interfaces
- Simulation and testbed-based experiments
- Explore and discover interdependencies across research areas.

Cross Cutting Themes:

- Learning and Autonomous Networking





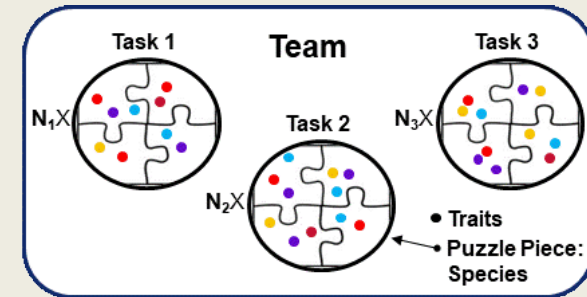
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Some Expected Outcomes

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New Theories for Composable Autonomy in Heterogeneous Groups

- Develop abstractions of species by decomposing them into a collection of re-composable traits.
- Develop abstractions of composable human traits, which accommodate general and evolving individualized profiles



New Approaches for Mission Planning with Large Scale Heterogeneous Teams

- Dynamic methods of mapping high-level mission requirements to abstractions (traits) used to synthesize action plans & task requirements for distributed agents

Human-Agent Collaborative Control of the Swarm

- Interaction architecture that makes large scale swarms amenable to human control in dynamic, stochastic, and partially observable environments.

Heterogeneous Hierarchical Autonomous Networks

- Develop the tactical cloud thru the exploitation of heterogeneous communications strategies & computing capabilities

Large Scale Multi-Level Optimization and Fast Response to Changing Mission Requirements

- Enable multiple users influence of swarm organization.

Algorithms



Architectures



Models



Humans





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Some Expected Outcomes

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- **Dynamic online learning** that responds to rapid changes in the environment and is resilient to unexpected and adversarial information
- **Adaptive agent-based behaviors** that reason over rich representations of uncertainty to trade off performance and risk
- Techniques to ensure **macro-scale resilience** as a function of mobility, swarm size, heterogeneity, sensing, and communication.

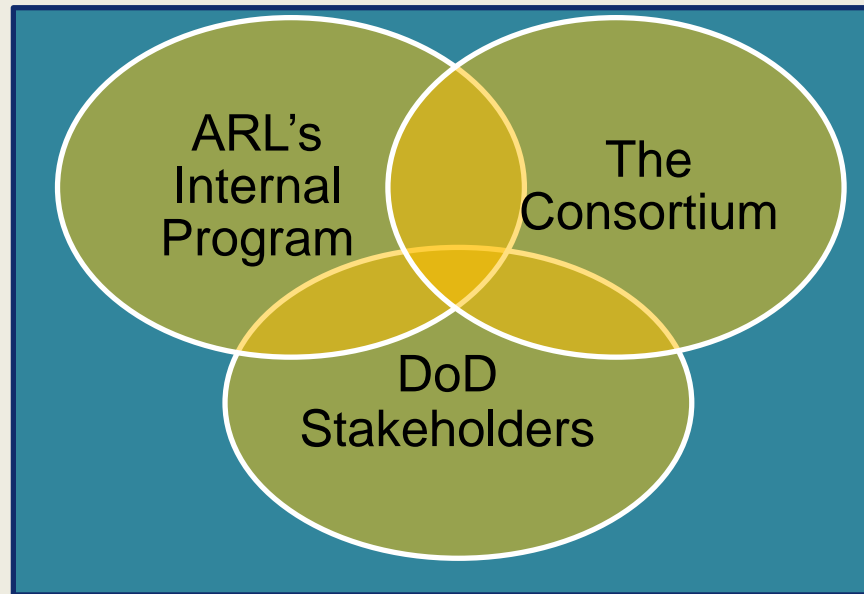


Impact

Distributed systems that are able to **engage in complex, time-varying, and contested environments** to accomplish Army missions by leveraging a mix of online adaptation and system-wide resilience.



- Collaboration between Consortium and Government researchers is integral to the execution and success of the CRA.
- The Consortium, ARL, and external stakeholders together form the Collaborative Research Alliance.
- ARL will fund in-house staff and align in-house research to foster highly collaborative partnerships between Consortium and Government researchers.

**Expectations:**

- Sharing of Data
- Staff Rotations
- Joint Experimentation
- Joint Publications

The Alliance



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DCIST CRA: The Consortia

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LRO: University of Pennsylvania

LRAO RA1 – MIT

LRAO RA2 – Georgia Tech

LRAO RA3 – UPenn

6 Institutions – 20 Researchers

UPenn: Drs. Bassett, Daniilidis, Kumar, Pappas, Ribeiro, and Hsieh

MIT: Drs. Roy, Carlone, How, Shah, and Karaman

Georgia Tech: Drs. Chernova, Egerstedt, Romberg, and Tsiotras

USC: Drs. Ayanian and Sukhatme

UCB: Dr. Levine

UCSD: Drs. Christensen and Atanasov

Status

- Initial Program Plan in preparation
- 6.1 Basic Research Funding
- 5 years, renewable for 5 years

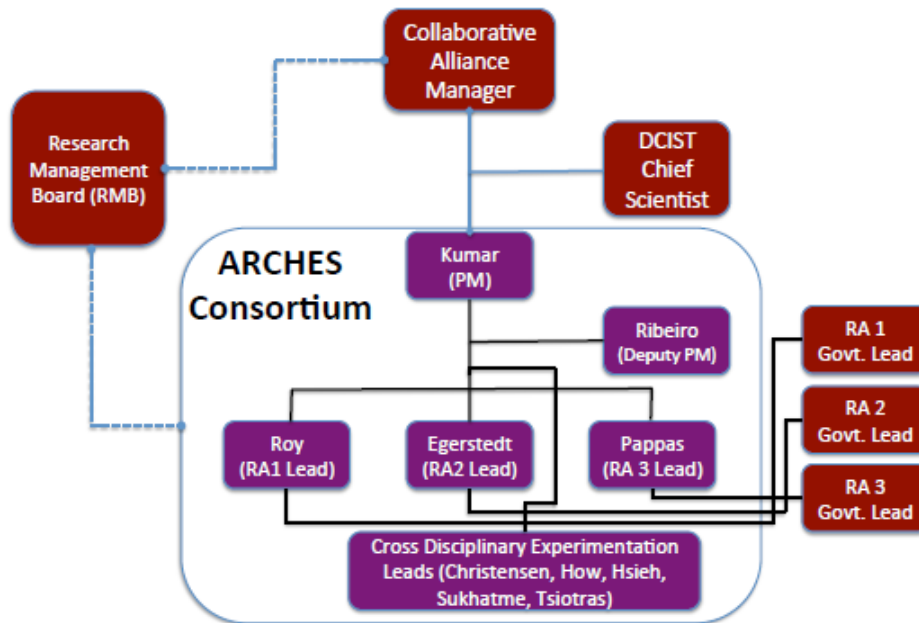


Figure 15: The DCIST Alliance.

Consortia + ARL + DoD Stakeholders = The Alliance



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Technical Management Group (TMG) **ARL**

	ARL Leadership	Consortium Leadership
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RA3 - Adaptive and Resilient Behaviors	Jonathan Fink (301) 394-5616 jonathan.r.fink3.civ@mail.mil	George Pappas (UPenn) (215) 898-9780 pappasg@seas.upenn.edu
Cross Disciplinary Experimentation	Jonathan Fink (301) 394-5616 jonathan.r.fink3.civ@mail.mil	TBD



Research Area 1 (RA1): Distributed Intelligence

RA1.A1 The Swarm's Knowledge Base: Contextual Perceptual Representations

RA1.A2 Hierarchical, Composable, and Adaptable Learning

RA1.A3 Hierarchical and Composable Planning for Sufficient Optimality

RA1.B1 Distributed Learning, Inference and Planning

RA1.B2 Collaborative Learning in Multi-Agent Networks

RA1.B3 Interaction with Human Teammates

RA1.C1 Joint Resource Allocation in Perception-Action-Communication Loops

RA1.C2 Resource-Aware Perception-Action-Communication Loops

RA1.C3 Adaptation and Learning in Wireless Autonomous Systems

Research Area 2 (RA2) : Heterogeneous Group Control

RA2.A1 Abstraction of Task Diversity

RA2.A2 Modeling Human Traits

RA2.A3 Composable Autonomy in Heterogeneous Groups

RA2.B1 Human-Agent Collaborative Control of the Swarm

RA2.B2 Heterogeneous Hierarchical Autonomous Networks

RA2.C1 Task Assignment



Research Area 3 (RA3): Adaptive and Resilient Behaviors

RA3.A1 Robust Adaptive Machine Learning

RA3.A2 Robust Self-Improving Inference, Perception, and Action

RA3.B1 Adaptive Swarm Behaviors for Uncertainty Mitigation

RA3.C1 Resilient Situational Awareness

RA3.C2 Resilience to Failures of Subsets of Network

Cross Disciplinary Experimentation (CDE)

CDE.1 Plug-and-Play Interfaces for Experimental Platforms

CDE.2 Integration of Wireless Communication Simulators

CDE.3 Develop Common Test Environments and Cases

CDE.4 Mobile Autonomous Networks

**6.1 Basic Research Program:**

- Funded by a cooperative agreement
- 5 year initial program
 - Option for 5-year extension
- Enhanced Research Program
 - Supplemental Research Tasks

Funding Category	Core Research Program (\$M)					
	Fiscal Year					
	FY18*	FY19	FY20	FY21	FY22	Total (10yr)
Basic Research (6.1)	3.6	5.2	5.5	5.7	6.1	26.1

- BPP funding is subject to the availability of funds.
- Estimated funding levels are for the Basic Research (6.1) Core Research Program.
- Funding execution is reviewed against OSD obligation and expenditure goals.



Enhanced Research Program

- Should additional funding for the DCIST CRA become available from ARL and OGAs, an Enhanced Research Program Funding provision is included for Budget Activity 1 and 2.
- Provides a mechanism for growth and enhancement within the CRA.
- May be basic and/or applied research dollars.
- This Enhanced Research Program will leverage and/or transition the research, technology and capabilities from the Core CRA Research Program.

	Enhanced Research Program (\$M)					
	FY18*	FY19	FY20	FY21	FY22	Total
Basic Research (6.1)	1.0	1.0	1.0	1.0	1.0	5.0
Applied Research (6.2)	2.0	2.0	2.0	2.0	2.0	10.0
Enhanced Total	3.0	3.0	3.0	3.0	3.0	15.0

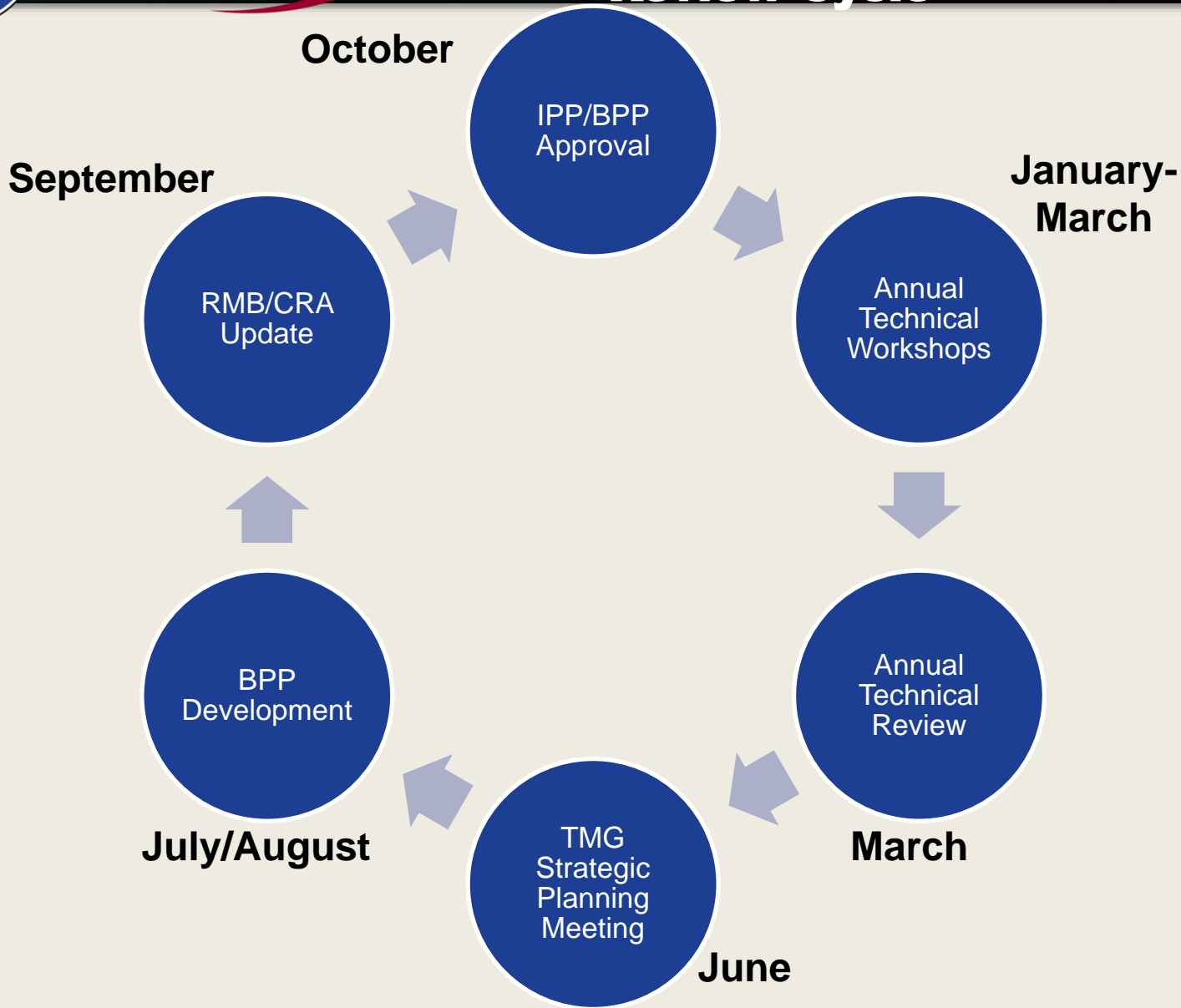


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DCIST CRA Planning and Review Cycle

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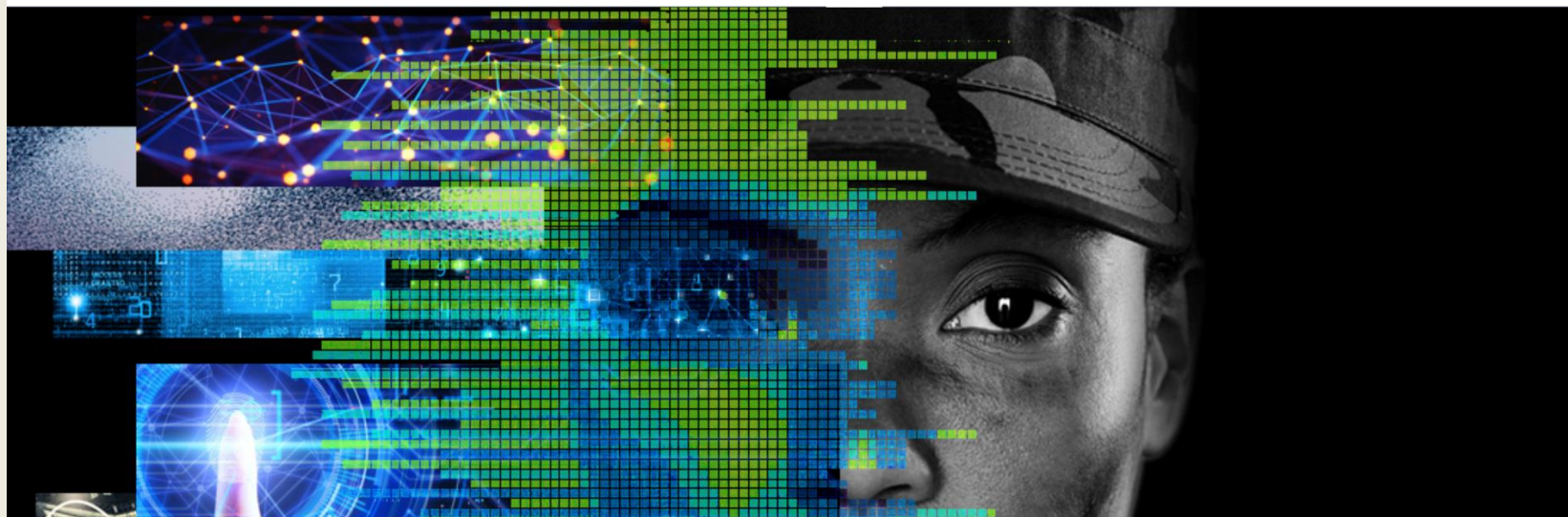
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The Distributed and Collaborative Intelligent Systems and Technology Collaborative Research Alliance (CRA) will create Autonomous, Resilient, Cognitive, Heterogeneous Swarms that can enable humans to participate in wide range of missions in dynamically changing, harsh, and contested environments. These include search and rescue of hostages, information gathering after terrorist attacks or natural disasters, and humanitarian missions.

Swarms of humans and robots will operate as a cohesive team with robots preventing humans from coming in harms way (Force Protection) and extending and amplifying their reach to allow one human to do the work of ten humans (Force Multiplication). Our research will create swarms that will provide on-demand services in these missions.

